

### **MLFB-Ordering data**

6SL3210-1KE17-5AP1



Figure similar

Client order no.: Order no.: Offer no.: Remarks:

Item no.: Consignment no.: Project:

Rated data		General tech. specifications		
nput		Power factor λ	0.70 0.85	
Number of phases	3 AC	Offset factor cos φ	0.95	
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.97	
Line frequency	47 63 Hz	Sound pressure level (1m)	52 dB	
Rated current (LO)	9.50 A	Power loss	0.14 kW	
Rated current (HO)	8.20 A	Amabian	nt conditions	
Output		Ambier	nt conditions	
Number of phases	3 AC	Cooling	Air cooling using an integrated fan	
Rated voltage	400 V		0.005 31 (0.477 (131)	
Rated power IEC 400V (LO)	3.00 kW	Cooling air requirement	0.005 m³/s (0.177 ft³/s)	
Rated power NEC 480V (LO)	4.00 hp	Installation altitude	1000 m (3280.84 ft)	
Rated power IEC 400V (HO)	2.20 kW	Ambient temperature		
Rated power NEC 480V (HO)	3.00 hp	Operation	-10 40 °C (14 104 °F)	
Rated current (IN)	7.50 A	Transport	-40 70 °C (-40 158 °F)	
Rated current (LO)	7.30 A	Storage	-40 70 °C (-40 158 °F)	
		Relative humidity		
Rated current (HO)	5.60 A		95 % At 40 °C (104 °F), condensation	
Max. output current	11.20 A	Max. operation	and icing not permissible	
Pulse frequency	4.000 kHz			
Output frequency for vector control	0 240 Hz	Closed-loop o	Closed-loop control techniques	
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parame	e <b>terizable</b> Yes	
		V/f with flux current control (FC	CC) Yes	
		V/f ECO linear / square-law	Yes	
overload capability		Sensorless vector control	Yes	

## Overload capability

# Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

#### High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Torque control, with encod	er No				
Communication					
Communication	PROFIBUS DP				

No

No

Vector control, with sensor

**Encoderless torque control** 



#### MLFB-Ordering data

Degree of protection

Standard digital inputs

Switching level: 0→1

Switching level: 1→0

Max. inrush current

Fail-safe digital inputs

Output (resistive load)

Number as transistor

Output (resistive load)

Analog / digital inputs

Number as relay changeover contact

Size

Width

Height

Depth

Number

Number

Number

Number

**Digital outputs** 

Net weight

6SL3210-1KE17-5AP1

IP20 / UL open type

1.70 kg (3.75 lb)

73 mm (2.87 in)

196 mm (7.72 in)

203 mm (7.99 in)

FSA

11 V

5 V

15 mA

DC 30 V, 0.5 A

DC 30 V, 0.5 A

1 (Differential input)

1 (Non-isolated output)

Mechanical data

Inputs / outputs



nections
0.15 1.50 mm² (AWG 24 AWG 16)
Plug-in screw terminals
1.00 2.50 mm² (AWG 18 AWG 14)
Plug-in screw terminals
1.00 2.50 mm² (AWG 18 AWG 14)
Plug-in scrow terminals

Motor end
Version
Conductor cross-section
DC link (for braking resi
Version
Conductor cross-section
Line length, max.
PE connection
Max. motor cable lengt
Shielded
Unshielded

Signal cable

Line side

Version

Conductor cross-section

Conductor cross-section

OC link (for braking resistor)					
Version	Plug-in screw terminals				
Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)				
Line length, max.	15 m (49.21 ft)				
PE connection  Max. motor cable length	On housing with M4 screw				
<b>j</b>					
Shielded	150 m (492.13 ft)				
Unshielded	150 m (492.13 ft)				
Standards					
Compliance with standards	UL, cUL, CE, C-Tick (RCM)				
CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC				

**Connections** 

# PTC/ KTY interface

**Analog outputs** 

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy ±5 °C



## **MLFB-Ordering data**

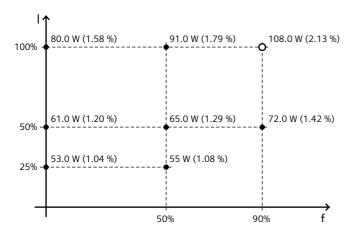
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Figure similar

## Converter losses to EN 50598-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-68.30 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values